

## Laser distance sensor

OPTIMESS S3 CCD



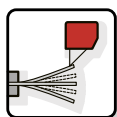
- High measuring rate
- Meets the highest requirements
- Digital processing of measured values
- Analog output or CAN bus

The opto-electronic sensor OPTIMESS S3 is a device for non-contact distance measurement. This sensor distinguishes itself by a great independence of the measurement accuracy on different material surfaces and from the ambient light.

The OPTIMESS S3 works according to the triangulation principle. The laser spot projected by a laser diode via an optical system is represented at an angle on a linescan image sensor by a receiving optical system. The processor integrated in the sensor processes the optical distance information and outputs them as an analog value or via the CAN bus.



Dynamic contour measurement



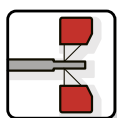
Vibration measurement



Steel industry, industrial automation



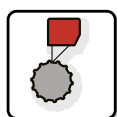
Distance measurement, position control



Thickness measurement



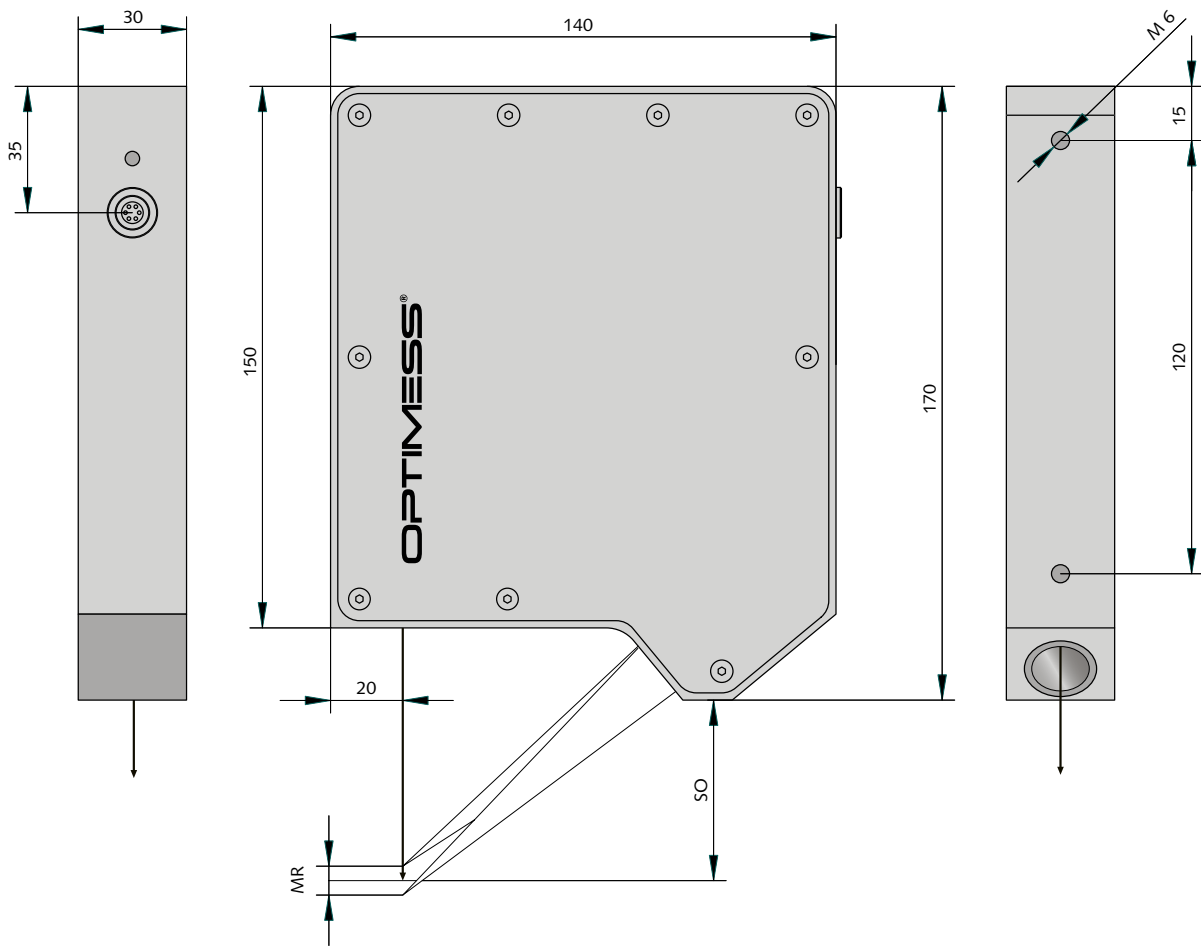
Rubber and tire industry



Profile measurement



Car industry



#### Technical data

	OMS 5804	OMS 5808	OMS 5812	OMS 5820	OMS 5840	OMS 5880
Measuring range [mm] [3]	4	8	12	20	40	80
Stand off [mm] [3]	20	20	50	50	100	150
Resolution [mm] [1]	0.001	0.002	0.003	0.005	0.010	0.020
Linearity	≤ ± 0.04% FSO					
Reproductibility	≤ ± 0.02% FSO					
Bandwidth [2]	20 kHz max.					
Filter [2]	Digital averaging					
Measuring rate	20 kHz max.					
Light source	Laser diode					
Spot diameter [2]	0.01–0.5 mm					
Wave-length [2]	660–780 nm					
Laser safety class [2]	2 / 3R / 3B					
Photo detector	CMOS Linear image sensor					
Supply voltage	± 15 V / 120 mA, ± 5% or 12–30 V / 120 mA [4]					
Output [2]	± 5 V / ± 10 V / 0–5V / 0–10 V / 0–20 mA / 4–20 mA / CAN - Bus					
Operating temperature	-20°C bis 50°C (no condensation)					
Dimensions	140 x 170 x 30 mm					
Weight	approx. 920 g					
Protection class	IP 54 / IP 65					

[1] Standard settings with filter 1Hz [2] Factory-set depending on the application [3] Other types upon request  
 [4] only unipolar output and CAN Bus